

# Review of Probability

ECE57000: Artificial Intelligence

David I. Inouye

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# Announcements

- ▶ Quiz 3 on Monday (Sep. 23)
- ▶ Updated syllabus
  - ▶ No longer require scikit-learn interface
  - ▶ Can use any Python libraries (e.g., PyTorch, TensorFlow or Keras)
- ▶ Paper selection grades are out

Note: Conditional and marginal distributions can be computed for *any set of variables*

► Suppose  $p(\mathbf{x}) = p(x_1, x_2, x_3, x_4)$

$$p(x_1, x_3) = \int_{x_2, x_4} p(\mathbf{x}) dx_2 dx_4$$

$$\begin{aligned} p(x_1, x_2 | x_3) &= \frac{p(x_1, x_2, x_3)}{p(x_3)} \\ &= \frac{\int_{x_4} p(\mathbf{x}) dx_4}{\int_{x_1, x_2, x_4} p(\mathbf{x}) dx_1 dx_2 dx_4} \end{aligned}$$

## Chain rule (or product rule) of probability

- ▶ The joint distribution can be written as product of conditional PDFs/PMFs:

$$p(x_1, x_2) = p(x_1)p(x_2|x_1)$$

$$p(x_1, x_2, x_3) = p(x_1)p(x_2|x_1)p(x_3|x_1, x_2)$$

- ▶ This can be written as:

$$p(x_1, x_2, \dots, x_d) = \prod_{i=1}^d p(x_i|x_1, \dots, x_{i-1})$$

- ▶ Consequence (order doesn't matter):

$$p(x)p(y|x) = p(y)p(x|y)$$

Bayes rule: Enables conversion between one conditional and the other (they are *different*)

$$p(x|y) = \frac{p(y|x) p(x)}{p(y)}$$

(derive on board, show reverse)

When are  $p(x|y)$  and  $p(y|x)$  equal?

Independence means that one variable is not affected by the other variable

- ▶ Example: Flip two coins,  $X$  and  $Y$  are 0 or 1.
- ▶ Counterexample: Roll dice for number  $X$ ; then flip that number of coins and count the number of heads  $Y$ .

- ▶ Formally, PDF/PMF can be written as product of functions that only involve  $x$  or  $y$  (but not both)

$$p(x, y) = f(x)f(y)$$

- ▶ Usually, these are the marginal densities:

$$p(x, y) = p(x)p(y)$$

- ▶ Equivalent definition:

$$p(x|y) = p(x) \text{ and } p(y|x) = p(y)$$

Two variables are conditionally independent if they are independent conditioned on a third variable

▶ Example: Person A is home late (event  $X$ ), Person B is home late (event  $Y$ ), snowstorm hits West Lafayette (event  $Z$ )

▶ Formally,  $X$  and  $Y$  are conditionally independent given  $Z$  if:

$$p(x, y, z) = f(x, z)f(y, z)$$

$$p(x, y|z) = p(x|z)p(y|z)$$

▶ Notation: Independence  $X \perp Y$

▶ Notation: Conditional independence  $X \perp Y | Z$

An expectation (or expected value) of a function of a random variable is the average or mean value with respect to its distribution

► Formal definitions

$$\mathbb{E}_{X \sim P(x)}[f(x)] \equiv \sum_{x \in X} f(x)P(x)$$
$$\mathbb{E}_{X \sim p(x)}[f(x)] \equiv \int_{x \in X} f(x)p(x)dx$$

- Sometimes drop notation to  $\mathbb{E}_X[f(x)]$  or just  $\mathbb{E}[f(x)]$  if clear from context
- Common: Mean of the distribution  $\mu = \mathbb{E}[x]$
- Examples:  $P(x) = [0.4, 0.3, 0.1, 0.3]$ ,  $p(x) = 3x^2$



Expectation is a *linear operator*

(i.e. splits on summation and scale can come out)

- ▶ A linear operator  $H$  must satisfy two properties:

$$H(f(x) + g(x)) = H(f(x)) + H(g(x))$$

$$H(\alpha f(x)) = \alpha H(f(x))$$

- ▶ Derive for matrix operator and vector
- ▶ Derive for expectations, i.e. when  $H = \mathbb{E}$

Variance measures the “spread” of a distribution

► Definition

$$\begin{aligned}\text{Var}[x] &= \sigma^2 \equiv \mathbb{E}_X[(x - \mu)^2] \\ &= \mathbb{E}_X[(x - \mathbb{E}_X[x])^2]\end{aligned}$$

► Intuitively, recenter and then measure expected value of  $f(x) = x^2$

► Standard deviation is square root of variance

$$\sigma = \sqrt{\sigma^2} = \sqrt{\mathbb{E}_X[(x - \mu)^2]}$$

# Covariance and correlation measure *linear* relationship between two variables

- ▶ Covariance definition

$$\text{Cov}[x, y] \equiv \sigma_{X,Y}^2 \equiv \mathbb{E}_{X,Y}[(x - \mu_X)(y - \mu_Y)]$$

- ▶ Correlation is a normalized covariance

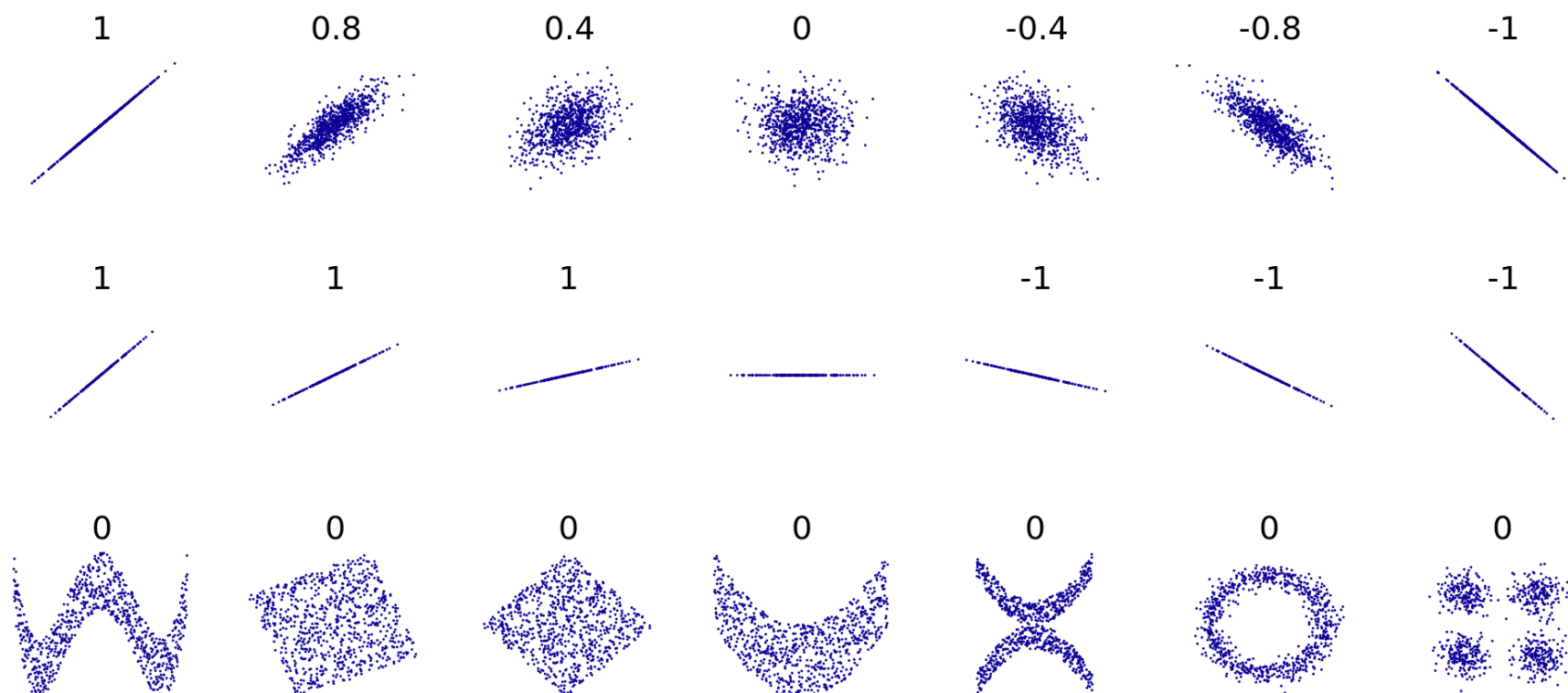
$$\rho_{X,Y} \equiv \frac{\sigma_{X,Y}^2}{\sigma_X \sigma_Y}$$

- ▶ Example:  $P(x, y) = [[0.4, 0.1], [0.1, 0.4]]$

- ▶  $\mu_X = \mu_Y = 0.5, \sigma_X^2 = \sigma_Y^2 = 0.25$

- ▶  $\sigma_{X,Y}^2 = -\frac{3}{20}, \rho_{X,Y} = -\frac{3}{5}$

Uncorrelated ( $\rho_{X,Y} = 0$ ) is **NOT** the same as independence (because only measures *linear* relationship)



# Covariance and correlation matrix

are generalizations for vectors

- ▶ Covariance matrix has covariance of every pair of random variables

$$\Sigma = \begin{bmatrix} \sigma_{X_1, X_1}^2 & \cdots & \sigma_{X_1, X_d}^2 \\ \vdots & \ddots & \vdots \\ \sigma_{X_d, X_1}^2 & \cdots & \sigma_{X_d, X_d}^2 \end{bmatrix}$$

- ▶ Matrix has variance along diagonal  $\sigma_{X_i, X_i}^2 = \sigma_{X_i}^2$
- ▶ Correlation matrix is similar but with 1s on diagonal

$$R = \begin{bmatrix} 1 & \cdots & \rho_{X_1, X_d} \\ \vdots & \ddots & \vdots \\ \rho_{X_d, X_1} & \cdots & 1 \end{bmatrix}$$

- ▶ Both matrices are symmetric  $\Sigma = \Sigma^T$  and  $R = R^T$

The empirical distribution and empirical expectation are *sampled* versions of their counterparts

- ▶ Dirac delta function is a point mass at  $\mu$

$$\delta(x - \mu) \equiv \lim_{\sigma^2 \rightarrow 0^+} \mathcal{N}(x; \mu, \sigma^2)$$

- ▶ **Empirical distribution** is formed from samples  $\{x_i\}_{i=1}^n$

$$\hat{p}(x) = \frac{1}{n} \sum_{i=1}^n \delta(x - x_i)$$

- ▶ **Empirical expectation** is expectation with respect to the empirical distribution (i.e., average over samples)

$$\hat{\mathbb{E}}[f(x)] = \int_x f(x) \hat{p}(x) dx = \frac{1}{n} \sum_{i=1}^n f(x_i)$$

Informally, entropy measures the “amount of randomness/disorder” of a distribution

- ▶ Formally, entropy for discrete variables

$$H(P(x)) = \mathbb{E}[-\log P(x)] = \sum_x -P(x) \log P(x)$$

- ▶ Formally, differential entropy for continuous variables

$$H(p(x)) = \mathbb{E}[-\log p(x)] = \int_x -p(x) \log p(x) dx$$

- ▶ Consider fair coin vs coin where both sides are heads