

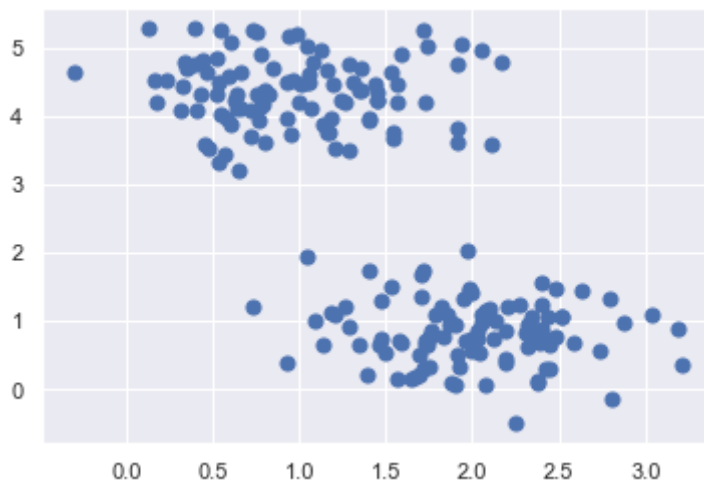
```
In [1]: import numpy as np
import matplotlib.pyplot as plt
import seaborn as sns
sns.set()
```

Consider a small "city" of people.

- Each point represents a person
- Friendships are formed entirely based on how close they live to each other

Could you put these people into communities?

```
In [2]: from sklearn.datasets.samples_generator import make_blobs
X, y_true = make_blobs(n_samples=200, centers=2,
                        cluster_std=0.50, random_state=0)
plt.scatter(X[:, 0], X[:, 1], s=50);
```



How would you tell a program to do what you did visually?

Remember how the computer "sees" these points

```
In [3]: # Print first 15 points
print(X[:15, :])
```

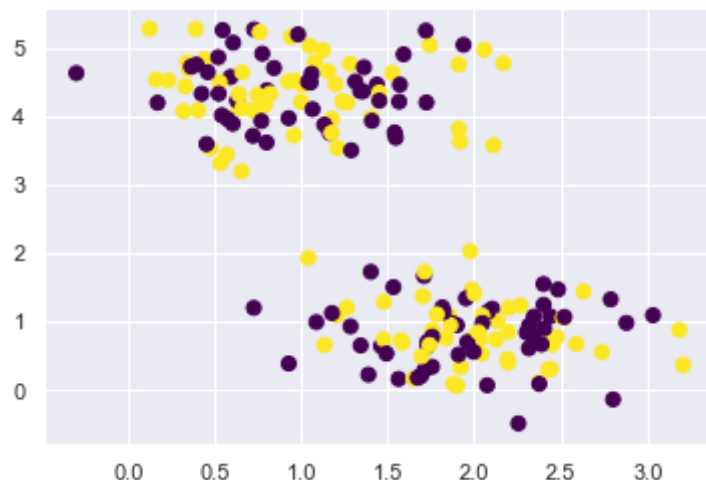
```
[[2.43859911 1.07581007]
 [1.85554301 1.0826916 ]
 [2.58952222 0.67097076]
 [1.73654901 0.69902775]
 [1.74265969 5.03846671]
 [0.64003985 4.12401075]
 [1.04829186 5.03092408]
 [0.5323772  3.31338909]
 [1.98882723 0.74876822]
 [0.16117091 4.53517846]
 [1.7571105  0.87138001]
 [1.28486901 0.92929466]
 [1.16448284 3.75408693]
 [0.3498724  4.69253251]
 [2.10413001 1.1891405  ]]
```

How do we formalize what we did visually?

- Let's assume for now that we know there are exactly *two* communities
- How can we assign each person to a community?
- Naive idea: Randomly assign points to each community

```
In [4]: from sklearn.utils import check_random_state
def get_random_assignment(random_state=None):
    rng = check_random_state(random_state)
    y = rng.randint(2, size=X.shape[0])
    return y
y_rand = get_random_assignment(random_state=0)
plt.scatter(X[:, 0], X[:, 1], c=y_rand, s=50, cmap='viridis')
```

```
Out[4]: <matplotlib.collections.PathCollection at 0x1a21957748>
```



This clustering "looks" quite bad.

How can we formalize whether a particular assignment is good or bad?

- One intuition: People in a communities will be as close to each other as possible.
- Take average distance between each person in a community to every other person in the **same** community.
- Sum over all communities.

Implement objective in via vectorized calls

$$C_j = \{x \in \mathcal{X} : y = j\}$$
$$\sum_{j=1}^k \frac{1}{2|C_j|} \sum_{x \in C_j, z \in C_j} \text{dist}(x, z)^2$$

```
In [5]: from sklearn.metrics import pairwise_distances
# Using vectorized and list comprehensions computation
def objective(X, y):
    y_vals = np.unique(y)
    def inner(yv):
        sel = (y==yv) # boolean array
        Xj = X[sel, :]
        n_community = np.sum(sel)
        community_sum = np.sum(pairwise_distances(Xj, Xj)**2)
        return community_sum / (2*n_community)
    return np.sum([inner(yv) for yv in y_vals])

print(objective(X, y_rand))
```

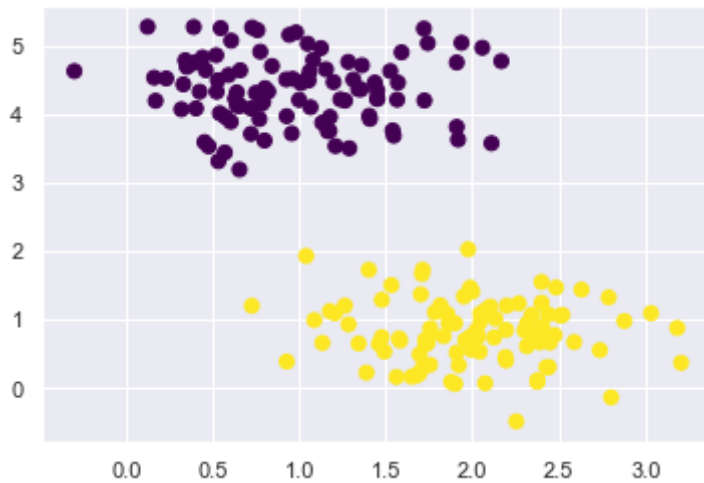
767.2572924351311

Intuition sanity check, does visual clustering solution have a low value?

```
In [6]: print(objective(X, y_true))
plt.scatter(X[:, 0], X[:, 1], c=y_true, s=50, cmap='viridis')
```

94.67363954089785

Out[6]: <matplotlib.collections.PathCollection at 0x1a2309c9e8>



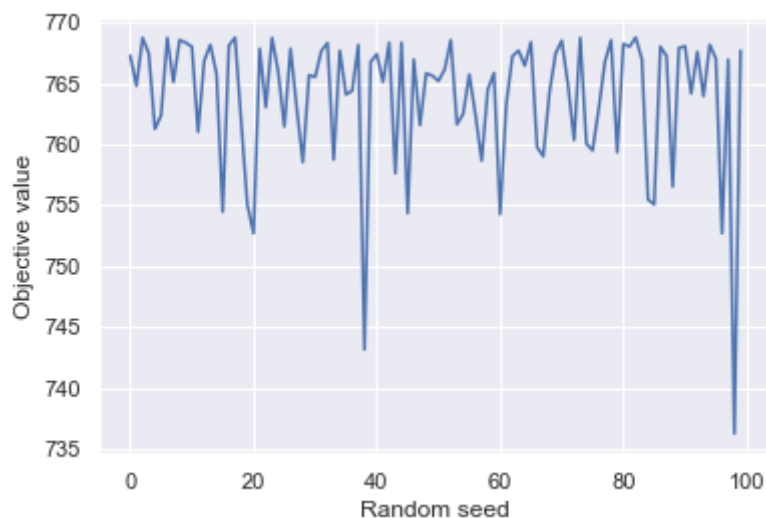
Clustering goal: Minimize objective over possible community assignments

$$\arg \min_{C_1, C_2} \sum_{j=1}^k \frac{1}{2|C_j|} \sum_{x \in C_j, z \in C_j} \text{dist}(x, z)^2$$

- Naively, we could just enumerate all possibilities
- Let's try several random combinations

```
In [7]: rand_obj = np.nan * np.ones(100)
for seed in range(rand_obj.shape[0]):
    y_rand = get_random_assignment(random_state=seed)
    rand_obj[seed] = objective(X, y_rand)
    #print('Seed = %2d, Objective = %g' % (seed, obj))
plt.plot(rand_obj)
plt.xlabel('Random seed')
plt.ylabel('Objective value')
#plt.scatter(X[:, 0], X[:, 1], c=y_rand, s=50, cmap='viridis')
```

Out[7]: Text(0, 0.5, 'Objective value')



How many possible assignments are there?

In terms of the number of samples n and the number of communities k

```
In [8]: n_samples = X.shape[0]
n_communities = 2
n_assignments = n_communities ** (n_samples-1)
print('For %d samples and %d communities, there are %d possible assignments
      % (n_samples, n_communities, n_assignments))
print('Or in exponential notation: %g possible assignments' % n_assignments)
```

For 200 samples and 2 communities, there are 8034690221294951377709810461
70581301261101496891396417650688 possible assignments
Or in exponential notation: 8.03469e+59 possible assignments

Some perspective: Fastest super computer is 200 petaflops = $2 * 10^{17}$ operations per second

```
In [9]: ops = 2 * (10 ** 17)
print(ops)
compute_time = n_assignments / ops
compute_time_years = compute_time / 60 / 60 / 24 / 365
print('Years of compute time: %d' % compute_time_years)
```

```
2000000000000000000
Years of compute time: 127389177785625178899305200808361984
```

Clearly, not a good way to optimize

Let's consider a *equivalent* optimization

Can you figure out what these two equations mean?

$$\mu_j \equiv \frac{1}{|C_j|} \sum_{x \in C_j} x_i$$

$$\arg \min_{C_1, C_2, \dots, C_k} \sum_{j=1}^k \sum_{x \in C_j} \text{dist}(x, \mu_j)^2$$

```
In [10]: # Just space holder
```

Consider an equivalent optimization via community *representatives*

- Intuition: Instead of measuring from each person to every other person in the same community, measure between a person and an ideal "representative" of each community, who is at the center of everyone.
- Representative can move freely.
- If the community assignments C_j are fixed, then the position of the "representative", denoted by μ_j is defines as the mean/average point:

$$\mu_j \equiv \frac{1}{|C_j|} \sum_{x \in C_j} x_i$$

- Given this definition of the representative, this leads to the following equivalent minimization:

$$\arg \min_{C_1, C_2, \dots, C_k} \sum_{j=1}^k \sum_{x \in C_j} \text{dist}(x, \mu_j)^2$$

$$\arg \min_{C_1, C_2, \dots, C_k} \sum_{j=1}^k \sum_{x \in C_j} \text{dist} \left(x, \frac{1}{|C_j|} \sum_{x \in C_j} x_i \right)^2$$

(Derivation of equivalence can be seen at

https://www.math.ucdavis.edu/~strohmer/courses/180BigData/180lecture_kmeans.pdf

(https://www.math.ucdavis.edu/~strohmer/courses/180BigData/180lecture_kmeans.pdf.)

Implement the objective of the equivalent optimization

$$\arg \min_{C_1, C_2, \dots, C_k} \sum_{j=1}^k \sum_{x \in C_j} \text{dist}(x, \mu_j)^2$$

```
In [11]: def objective2(X, y):
          k = len(np.unique(y))
          out = 0
          for j in range(k):
              sel = (y==j) # boolean array
              Xj = X[sel, :]
              mu_j = np.mean(Xj, axis=0)
              dist_to_mu = np.sqrt(np.sum((Xj - mu_j)**2, axis=0))
              out += np.sum(dist_to_mu**2)
          return out

          print('Quick sanity check that objective corresponds to visual understanding')
          print('Objective random', objective2(X, y_rand))
          print('Objective visual', objective2(X, y_true))
```

Quick sanity check that objective corresponds to visual understanding

Objective random 767.679899871254

Objective visual 94.67363954089788

Let's suppose the representative can move around and the communities haven't settled yet

$$\arg \min_{C_1, \dots, C_k, \mu_1, \dots, \mu_k} \sum_{j=1}^k \sum_{x \in C_j} \text{dist}(x, \mu_j)^2$$

- Two intuitive ideas in this "unsettled" state

1. People will join the community of their closest *representative* μ_j .

$$y_i = \arg \min_{j=\{1,2,\dots,k\}} \text{dist}(x_i, \mu_j)$$

2. The representative will move to the center of it's current community.

$$\mu_j = \frac{1}{|C_j|} \sum_{x \in C_j} x_i$$

```
In [12]: def objective3(X, y, mu_array):
          k = len(np.unique(y))
          out = 0
          for j in range(k):
              sel = (y==j) # boolean array
              Xj = X[sel, :]
              mu_j = mu_array[j, :]
              dist_to_mu = np.sqrt(np.sum((Xj - mu_j)**2, axis=0))
              out += np.sum(dist_to_mu**2)
          return out
```

Two intuitive ideas in this "unsettled" state

1. People will join the community of their closest *representative* μ_j .

$$y_i = \arg \min_{j=\{1,2,\dots,k\}} \text{dist}(x_i, \mu_j)$$

2. The representative will move to the center of it's current community.

$$\mu_j = \frac{1}{|C_j|} \sum_{x \in C_j} x_i$$

Let's assume the representatives don't know anything about the community so they just randomly choose to start in one house

(1) Assign people to their communities based on the representatives

```
In [13]: mu_array = np.array([[0, 1], [1, 0]])
          print(objective3(X, y_rand, mu_array))

          # Assign people
          def best_assignment(X, mu_array):
              y_best = np.argmin(pairwise_distances(X, mu_array), axis=1)
              return y_best

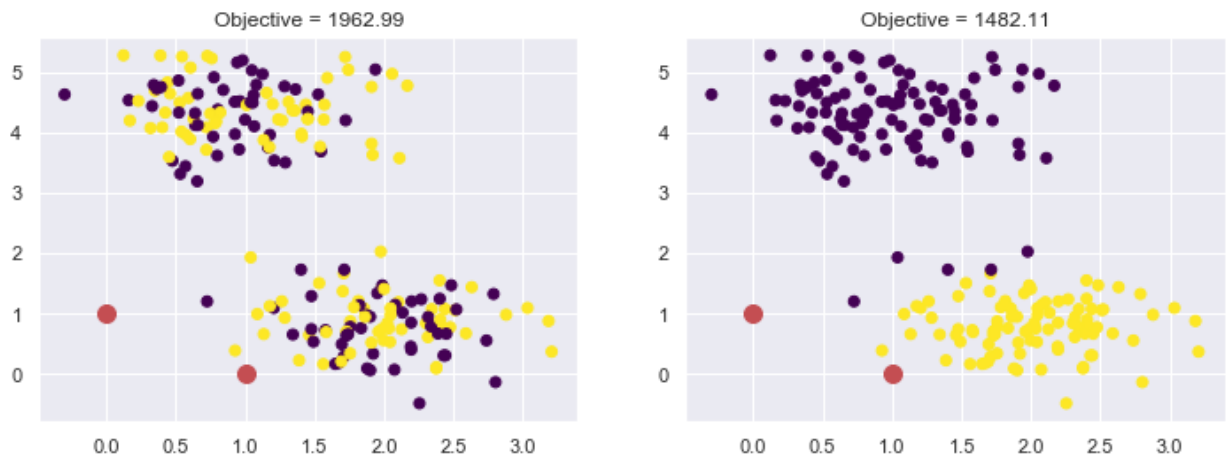
          y_new = best_assignment(X, mu_array)
          print(objective3(X, y_new, mu_array))
```

```
1962.992539917816
1482.1076321431726
```


Make simple function for plotting (use ax as argument)

```
In [14]: def plot_clustering(X, y, mu_array, ax=None):
    if ax is None:
        ax = plt.gca()
    ax.plot(mu_array[:, 0], mu_array[:, 1], 'ro', markersize=10)
    ax.scatter(X[:, 0], X[:, 1], c=y, cmap='viridis')
    ax.set_title('Objective = %g' % objective3(X, y, mu_array))

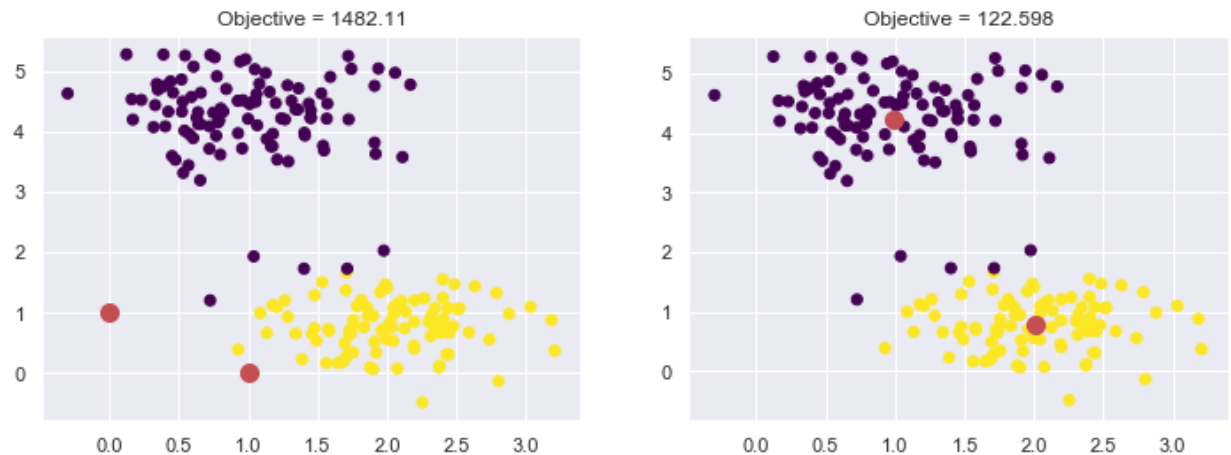
fig, axes = plt.subplots(1, 2, figsize=(12, 4))
for ycur, ax in zip([y_rand, y_new], axes):
    plot_clustering(X, ycur, mu_array, ax=ax)
```



(2) Now let's move the representative to the center of its community

```
In [15]: def recenter(X, y):
    return np.array([
        np.mean(X[y==yv, :], axis=0)
        for yv in np.unique(y)
    ])
mu_array_new = recenter(X, y_new)

fig, axes = plt.subplots(1, 2, figsize=(12, 4))
for m, ax in zip([mu_array, mu_array_new], axes):
    plot_clustering(X, y_new, m, ax=ax)
```



What do you think you should do next?

```
In [16]: # Program kmeans
def kmeans_alg(X, maxiter=100, random_state=None):
    rng = check_random_state(random_state)

    # Initialize with random points in X
    rand_idx = rng.permutation(X.shape[0])
    mu_array = X[rand_idx[:2], :]
    y = get_random_assignment(random_state=rng)

    for i in range(maxiter):
        # Get new best assignment
        y_old = y # Save old assignment matrix
        y = best_assignment(X, mu_array)

        # Recenter / compute cluster mean
        mu_array = recenter(X, y)

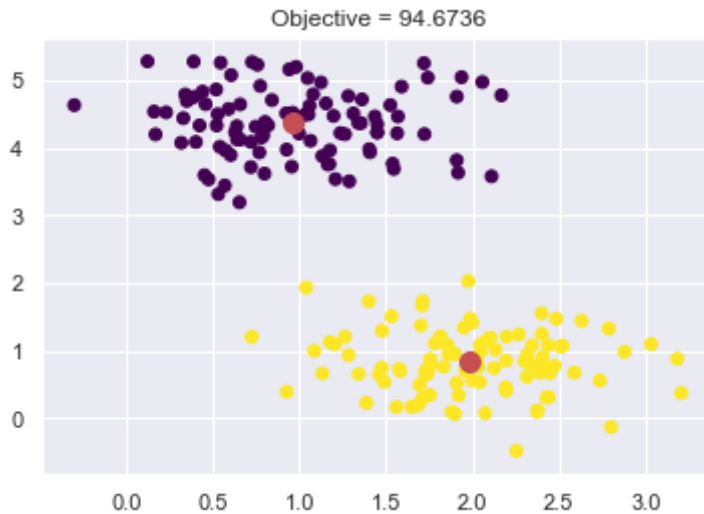
        # Check convergence
        if y_old is not None and np.all(y == y_old):
            print('Converged after %d iteration' % i)
            break
    return y, mu_array
```

```
In [17]: y_kmeans, mu_kmeans = kmeans_alg(X, maxiter=100, random_state=0)

plt.plot(mu_kmeans[:, 0], mu_kmeans[:, 1], 'ro', markersize=10)
plt.scatter(X[:, 0], X[:, 1], c=y_kmeans, cmap='viridis')
plt.title('Objective = %g' % objective3(X, y_kmeans, mu_kmeans))
```

Converged after 3 iteration

```
Out[17]: Text(0.5, 1.0, 'Objective = 94.6736')
```



Let's inspect the underlying operation by splitting the iteration

```
In [18]: # Program kmeans
def kmeans_alg(X, maxiter=100, random_state=None):
    rng = check_random_state(random_state)

    # Initialize with random points in X
    rand_idx = rng.permutation(X.shape[0])
    mu_array = X[rand_idx[:2], :]
    y = get_random_assignment(random_state=rng)

    for i in range(int(2*maxiter)): #CHANGED
        if i % 2 == 0: #CHANGED
            # Get new best assignment
            y_old = y # Save old assignment matrix
            y = best_assignment(X, mu_array)
        else: #CHANGED
            # Recenter / compute cluster mean
            mu_array = recenter(X, y)

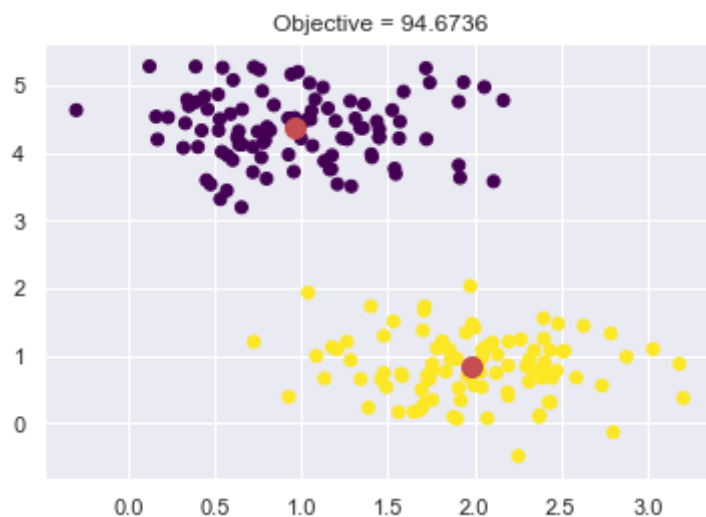
            # Check convergence
            if y_old is not None and np.all(y == y_old):
                print('Converged after %d iteration' % (i/2)) #CHANGED
                break
    return y, mu_array
```

```
In [19]: y_kmeans, mu_kmeans = kmeans_alg(X, maxiter=4, random_state=0)

plt.plot(mu_kmeans[:, 0], mu_kmeans[:, 1], 'ro', markersize=10)
plt.scatter(X[:, 0], X[:, 1], c=y_kmeans, cmap='viridis')
plt.title('Objective = %g' % objective3(X, y_kmeans, mu_kmeans))
```

Converged after 3 iteration

```
Out[19]: Text(0.5, 1.0, 'Objective = 94.6736')
```



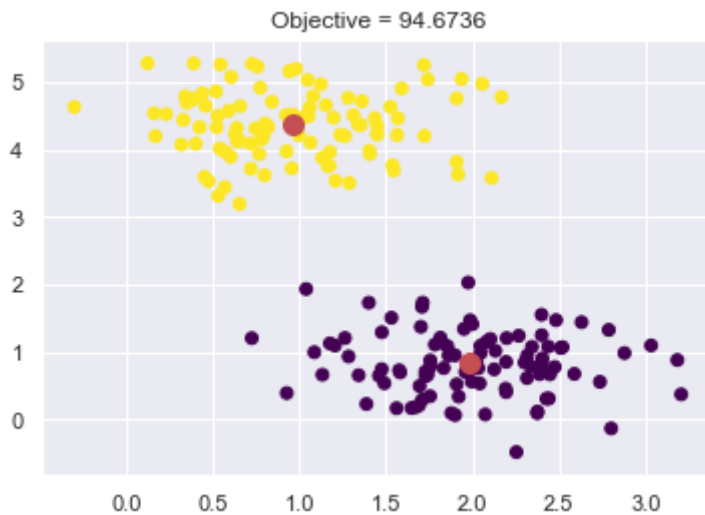
**Introducing scikit-learn's
sklearn.cluster.KMeans**

- Documentation: <https://scikit-learn.org/stable/modules/generated/sklearn.cluster.KMeans.html> (<https://scikit-learn.org/stable/modules/generated/sklearn.cluster.KMeans.html>) (some nice examples at the bottom of the documentation)
- See Python handbook for nice examples of kmeans <https://jakevdp.github.io/PythonDataScienceHandbook/05.11-k-means.html> (<https://jakevdp.github.io/PythonDataScienceHandbook/05.11-k-means.html>)

```
In [20]: from sklearn.datasets.samples_generator import make_blobs
X, y_true = make_blobs(n_samples=200, centers=2,
                       cluster_std=0.50, random_state=0)

from sklearn.cluster import KMeans
kmeans = KMeans(n_clusters=2, random_state=0) # 0 and 2 give opposite clust

kmeans.fit(X)
y_kmeans = kmeans.labels_
mu_array = kmeans.cluster_centers_
plot_clustering(X, y_kmeans, mu_array)
```

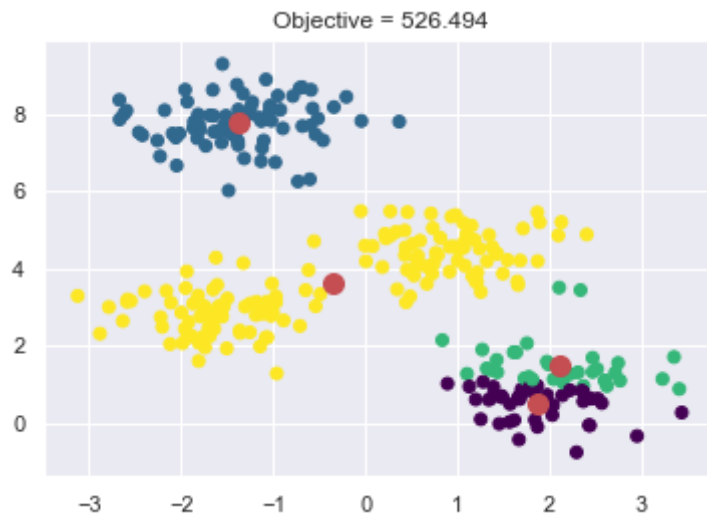


This looks great! But isn't this an NP-Hard problem?

First caveat: Does not always converge to the optimal/best solution.

```
In [21]: # Example from Python handbook
from sklearn.datasets.samples_generator import make_blobs
X2, y_true2 = make_blobs(n_samples=300, centers=4,
                        cluster_std=0.60, random_state=0)

kmeans = KMeans(n_clusters=4, init='random', n_init=1, random_state=104) #
kmeans.fit(X2)
plot_clustering(X2, kmeans.labels_, kmeans.cluster_centers_)
```



Second caveat: Choosing the number of clusters is not obvious

```
In [22]: # Example from Python handbook
from sklearn.datasets.samples_generator import make_blobs
X2, y_true2 = make_blobs(n_samples=300, centers=4,
                        cluster_std=0.60, random_state=0)

kmeans = KMeans(n_clusters=9, init='random', n_init=1, random_state=0)
kmeans.fit(X2)
plot_clustering(X2, kmeans.labels_, kmeans.cluster_centers_)
```



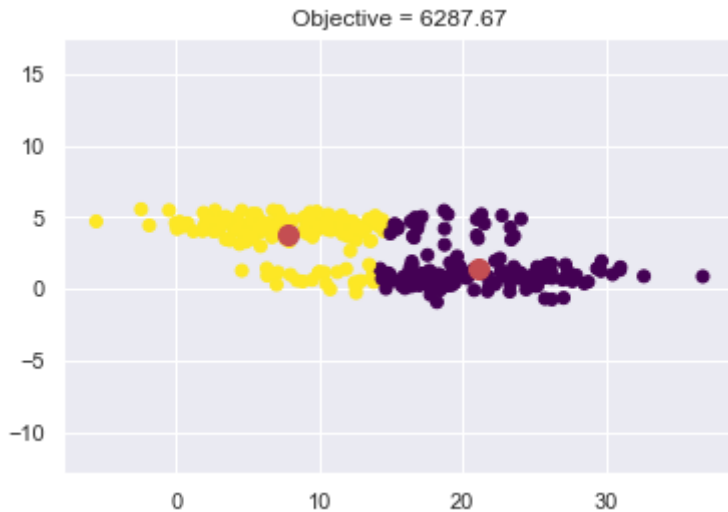
Third caveat: Scaling of variables and clusters matters

```
In [23]: from sklearn.datasets import make_moons
X3, y_true = make_blobs(n_samples=300, centers=2,
                        cluster_std=0.60, random_state=0)
X3[:, 0] = X3[:, 0]*10

kmeans = KMeans(n_clusters=2, random_state=0).fit(X3)

plot_clustering(X3, kmeans.labels_, kmeans.cluster_centers_)
plt.axis('equal')
```

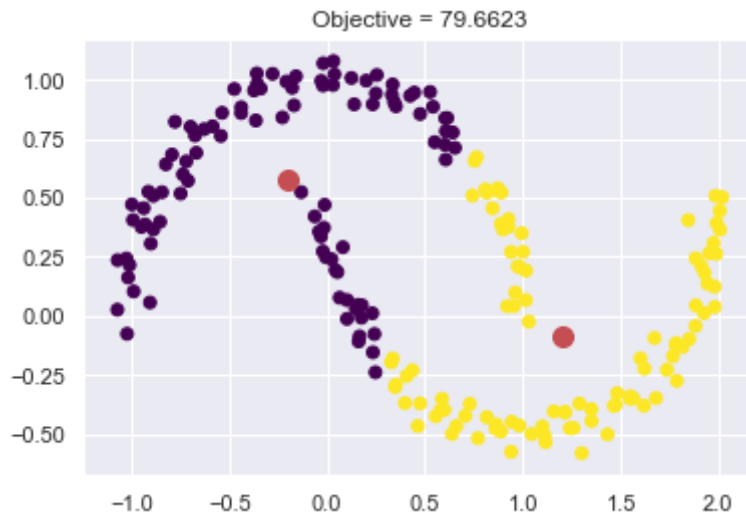
```
Out[23]: (-7.813474526935023,
          38.988255947105756,
          -1.2918715239530854,
          5.9043323952750475)
```



Fourth caveat: Only linear boundaries between clusters


```
In [24]: from sklearn.datasets import make_moons
X4, y_true4 = make_moons(200, noise=.05, random_state=0)

kmeans = KMeans(n_clusters=2, random_state=0).fit(X4)
plot_clustering(X4, kmeans.labels_, kmeans.cluster_centers_)
```



In []: