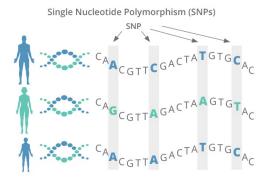
Unsupervised Dimensionality Reduction via PCA

ECE57000: Artificial Intelligence David I. Inouye Thursday, September 9, 2021 Very high-dimensional data is becoming ubiquitous

- Images (1 million pixels)
- Text (100k unique words)
- Genetics (4 million SNPs)
- Business data (12 million products)





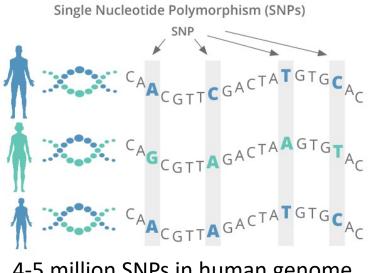




<u>Why</u> dimensionality reduction? Lower computation costs

 Suppose original dimension is large like d = 100000 (e.g., images, DNA sequencing, or text)

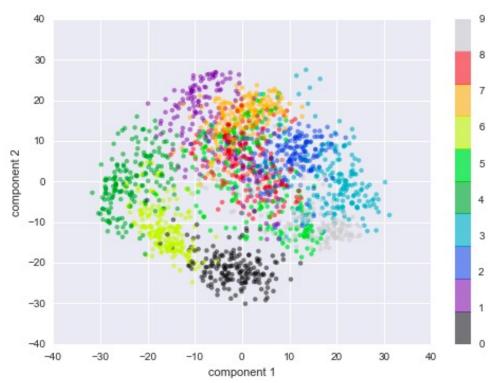
If we reduce to k = 100 dimensions, the training algorithm can be sped up by 1000×



4-5 million SNPs in human genome. https://www.diagnosticsolutionslab.com/tests/genomicinsight

<u>Why</u> dimensionality reduction? Visualization

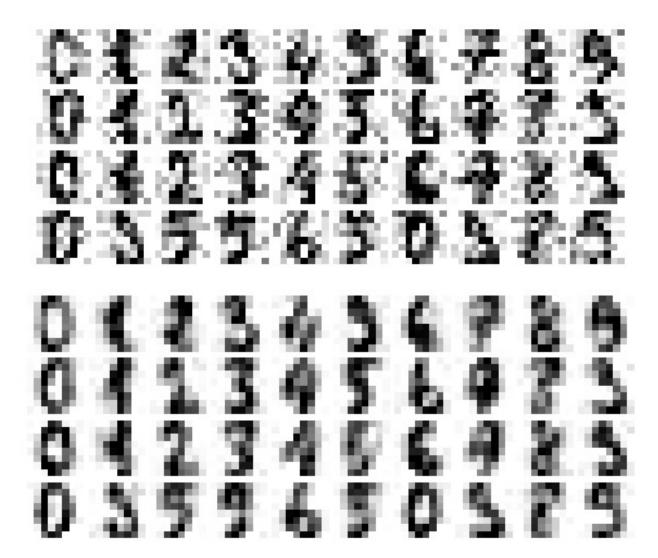
Allows 2D scatterplot visualizations even of high-dimensional data (2D projection of digits)



https://jakevdp.github.io/PythonDataScienceHandbook/05.09-principal-component-analysis.html

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<u>Why</u> dimensionality reduction? Noise reduction via reconstruction



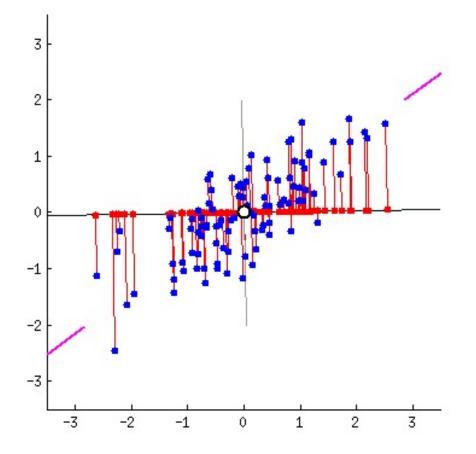
Outline of Principal Components Analysis (PCA)

- 1. Motivation for dimensionality reduction
- 2. Intuition of PCA
- 3. Formal PCA problem: Min reconstruction
- 4. Derive PCA formulation for 1D
 - Least error 1D projection is orthogonal
 - Sum over all data points
- 5. Solution is based on truncated SVD
- 6. Alternative viewpoint: Max variance
 - Derive equivalence
 - Derive equivalent solutions

Review of linear algebra and introduction to numpy Python library

See Jupyter notebook, which can be opened and run in Google Colab

Intuition: Principal component analysis finds the **best** <u>**linear projection**</u> onto a lower-dimensional space



2D to 1D projection: Red lines show the projection error onto 1D lines. PCA finds the line that has the smallest projection error (in this example, when it aligns with the purple).

https://stats.stackexchange.com/questions/2691/making-sense-of-principal-component-analysis-eigenvectors-eigenvalues

Math: <u>Principal Component Analysis (PCA)</u> can be formalized as minimizing the linear reconstruction error of the data using only $k \leq d$ dimensions

PCA can be formalized as

$$\min_{\mathbf{Z},\mathbf{W}} \| X_c - Z W^T \|_F^2$$

► where

 $\begin{aligned} X_c &= X - \mathbf{1}_n \mu_x^T \in \mathbb{R}^{n \times d} \quad (\text{centered input data}) \\ Z &\in \mathbb{R}^{n \times k} \quad (\text{latent representation or "scores"}) \\ W^T &\in \mathbb{R}^{k \times d} \quad (\text{principal components}) \\ w_s^T w_t &= 0, w_s^T w_s = \|w_s\|_2 = 1, \forall s, t \\ (\text{orthogonal constraint}) \end{aligned}$

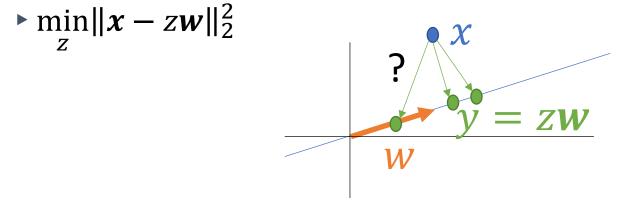
Math: <u>Principal Component Analysis (PCA)</u> can be formalized as minimizing the linear reconstruction error of the data using only $k \leq d$ dimensions

 $\min_{Z \in \mathbb{R}^{n \times k}, W \in \mathbb{R}^{d \times k}} \|X_c - ZW^T\|_F^2 \text{ s.t. } W^TW = I_k$

- Let's stare at this equation some more ③
- Why is this dimensionality reduction?
- What does the orthogonal constraint mean?
- Why minimize the squared Frobenius norm?
- $\|X_{c} ZW^{T}\|_{F}^{2} = \sum_{i=1}^{n} \|\mathbf{x}_{i}^{T} \mathbf{z}_{i}^{T}W^{T}\|_{2}^{2} = \sum_{i=1}^{n} \|\mathbf{x}_{i} W\mathbf{z}_{i}\|_{2}^{2}$
- For analysis, let's simplify to a single dimension (i.e., k = 1)
 - $\sum_{i=1}^{n} \|\mathbf{x}_{i} z_{i}\mathbf{w}\|_{2}^{2}$ where z_{i} is a scalar

What is the best projection given a fixed subspace (line in 1D case)?

► If we are given w, what is the best z (i.e. minimum reconstruction error) for a given x?



• The orthogonal projection! • $z = x^T w = ||x|| ||w|| \cos \theta = ||x|| \cos \theta$

$$\mathbf{z} = \mathbf{x}^{T} \mathbf{w} = \|\mathbf{x}\| \|\mathbf{w}\| \cos \theta = \|\mathbf{x}\| \cos \theta$$

$$\mathbf{r} z = \|\mathbf{x}\| \cos \theta = \operatorname{hyp} \cdot \frac{\operatorname{aug}}{\operatorname{hyp}} = \operatorname{ad}$$

zw is a scaled vector along the line defined by *w*

Thus, we can simplify to only minimizing over W

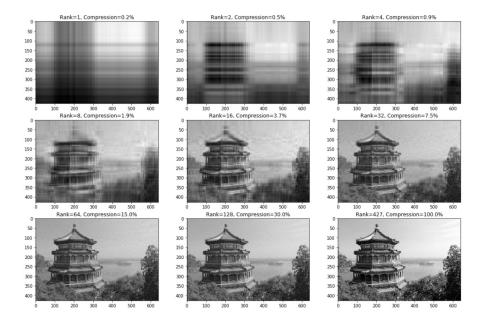
$$\min_{\mathbf{z},\mathbf{w}:\|\mathbf{w}\|_{2}=1} \sum_{i=1}^{n} \|\mathbf{x}_{i} - z_{i}\mathbf{w}\|_{2}^{2} = \min_{\mathbf{w}:\|\mathbf{w}\|_{2}=1} \sum_{i=1}^{n} \|\mathbf{x}_{i} - (\mathbf{x}_{i}^{T}\mathbf{w})\mathbf{w}\|_{2}^{2}$$

- Now we can return to the Frobenius norm: $\min_{\boldsymbol{w}: \|\boldsymbol{w}\|_2 = 1} \|X_c - \boldsymbol{z}\boldsymbol{w}^T\|_F^2 \text{ where } \boldsymbol{z} = X_c \boldsymbol{w}$
- What is zw^T ? Have we seen something like this before?
- This is the best low-rank approximation to X_c, which is given by the SVD!
 - $w = v_1$ and $z = \sigma_1 u_1$, where σ_1, u_1, v_1 are the first singular value, left singular vector and right singular vector respectively.

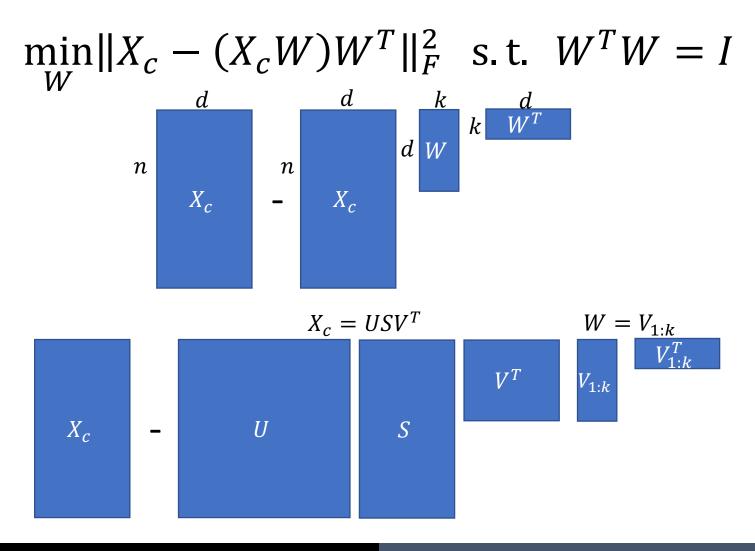
For $k \ge 1$, the PCA solution is the top k right singular vectors

• If
$$X_c = USV^T$$
, then the general solution is $W^* = V_{1:k}$

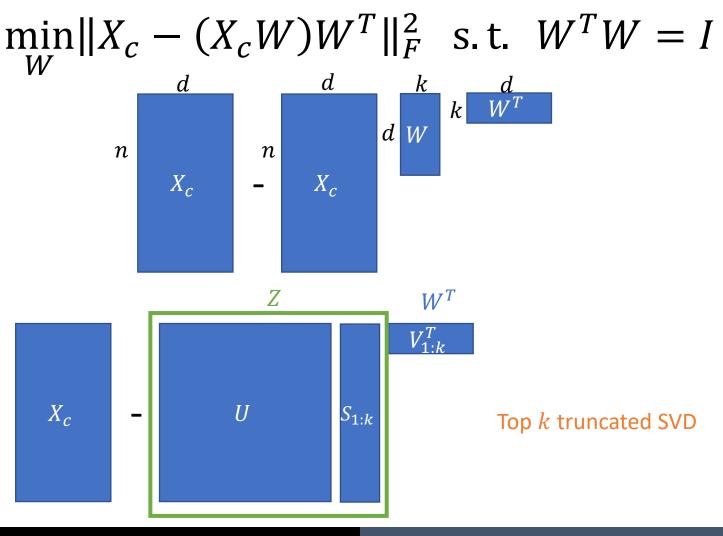
Remember: SVD is best k dim. approximation



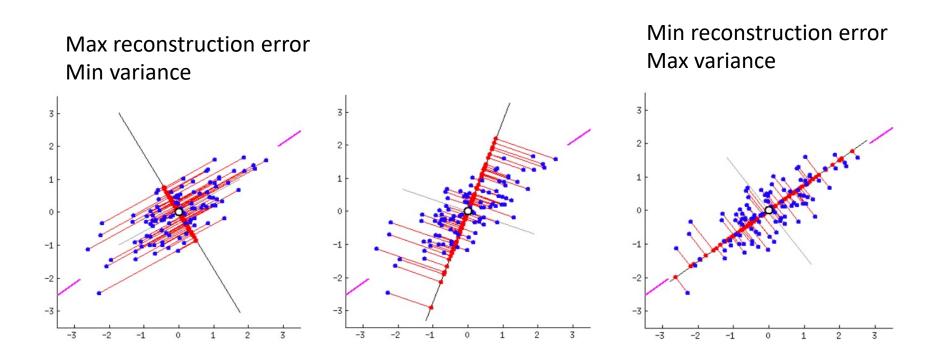
Check: The solution reveals the truncated SVD as best approximation



Check: The solution reveals the truncated SVD as best approximation



Claim: Minimizing reconstruction error (red lines) is equivalent to maximizing the variance of projection (spread of red points)



Derivation of min error equivalent to max variance

First step: Simplify squared distance

$$\|x_{i} - (x_{i}^{T}w)w\|_{2}^{2}$$

$$= (x_{i} - (x_{i}^{T}w)w)^{T}(x_{i} - (x_{i}^{T}w)w)$$

$$= x_{i}^{T}x_{i} - 2(x_{i}^{T}w)w^{T}x_{i} + (x_{i}^{T}w)^{2}w^{T}w$$

$$= \|x_{i}\|^{2} - 2(x_{i}^{T}w)^{2} + (x_{i}^{T}w)^{2}\|w\|^{2}$$

$$= \|x_{i}\|^{2} - (x_{i}^{T}w)^{2}$$

Derivation of min error equivalent to max variance

Equivalence of optimization in 1D

•
$$\arg\min_{w} \sum_{i} ||x_{i} - (x_{i}^{T}w)w||_{2}^{2}$$

• $= \arg\min_{w} \sum_{i} ||x_{i}||^{2} - (x_{i}^{T}w)^{2} = \arg\min_{w} \sum_{i} - (x_{i}^{T}w)^{2}$
• $= \arg\max_{w} \frac{1}{n} \sum_{i} (x_{i}^{T}w)^{2} = \arg\max_{w} \frac{1}{n} \sum_{i} z_{i}^{2}$
• $= \arg\max_{w} \sigma_{z}^{2}$
Note z is already centered so mean of squares is variance

Therefore, we can reformulate the problem as maximizing the variance

Let's rewrite this last term

$$\sigma_z^2 = \frac{1}{n} \sum_i (z_i)^2 = \frac{1}{n} \sum_i (x_i^T w)^2 = \frac{1}{n} (X_c w)^T (X_c w)$$
$$= w^T \left(\frac{1}{n} X_c^T X_c\right) w = w^T \widehat{\Sigma} w$$

Thus, our problem can be formulated as:

$$\max_{w:\|w\|=1} w^T \widehat{\Sigma} w$$

• The solution is the eigenvector q_1 of $\hat{\Sigma} = Q \Lambda Q^T$ corresponding to the largest eigenvalue λ_1

$$w^* = q_1$$

For k > 1, we maximize the sum of variances for each latent dimension

More generally we can formulate this as:

- $\max_{W:W^TW=I_k} \sum_{j=1}^k \sigma_{Z_j}^2$ $= \max_{W:W^TW=I_k} \sum_{j=1}^k w_j^T \widehat{\Sigma} w_j$ $= \max_{W:W^TW=I_k} \operatorname{Tr}(W^T \widehat{\Sigma} W)$
- $= \max_{W:W^TW=I_k} \operatorname{Tr}(W^T \widehat{\Sigma} W)$
- The solution is the top k eigenvectors of $\hat{\Sigma}$ = $Q \Lambda Q^T$

$$\blacktriangleright W^* = Q_{1:k}$$

Equivalent solutions: The solution to both problems is the top k right singular vectors of X_c

- Minimize reconstruction error $\min_{\substack{W:W^TW=I_k}} ||X_c - (X_cW)W^T||_F^2$
 - Singular value decomposition (SVD) of $X_c = USV^T$

Solution:
$$W^* = V_{1:k}$$

Maximize variance of latent projection

$$\max_{W:W^TW=I_k} \operatorname{Tr}(W^T\widehat{\Sigma}W)$$

Equivalent solution

$$n\hat{\Sigma} = X_c^T X_c = (USV^T)^T (USV^T) = (VSU^T)(USV^T) = VS(U^T U)SV^T = VS^2 V^T = Q\Lambda Q^T$$

Solution: $W^* = Q_{1:k} \equiv V_{1:k}!$

Recap: Principal Components Analysis (PCA)

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